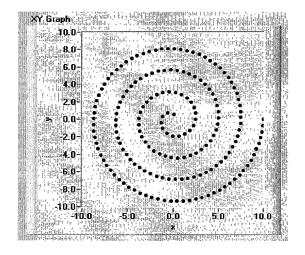


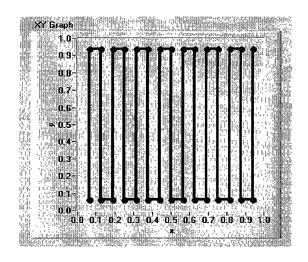
Approximated Peano Curve. The space-filling process has not been completed.

Figure 1A (Prior Art)



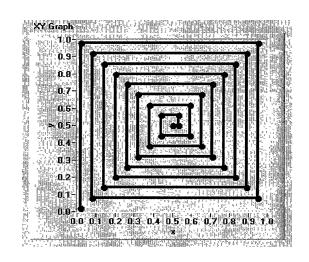
Archimedes Spiral defined by equally distributed points

Figure 1C (Prior Art)



Boustrophedon Path

Figure 1B (Prior Art)



Spiral-like line-based scanning

Figure 1D (Prior Art)

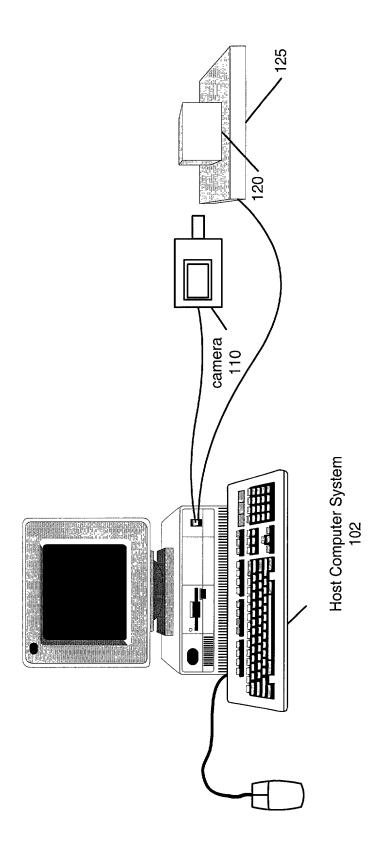


Figure 2A

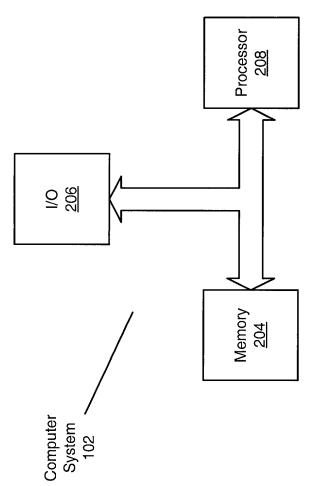


Figure 2B

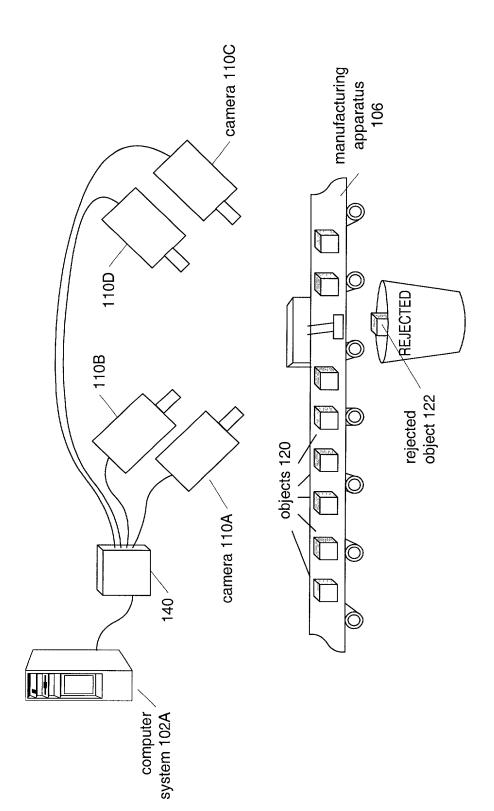


Figure 3A

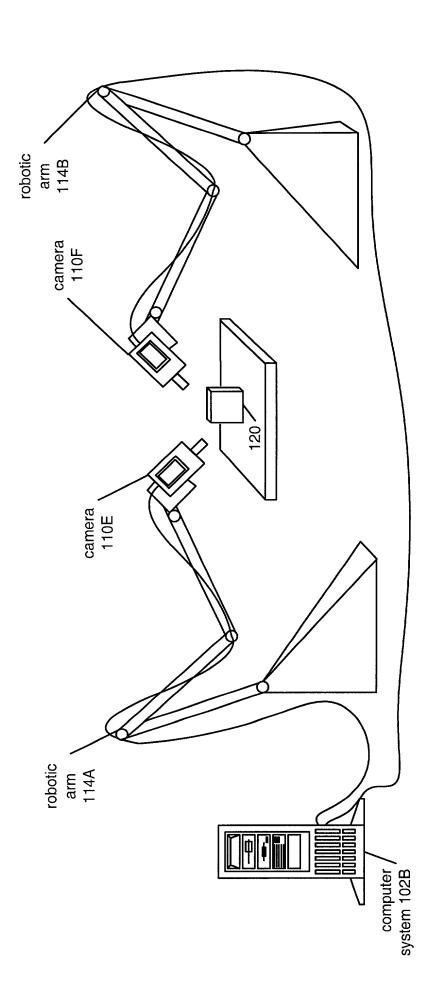


Figure 3B

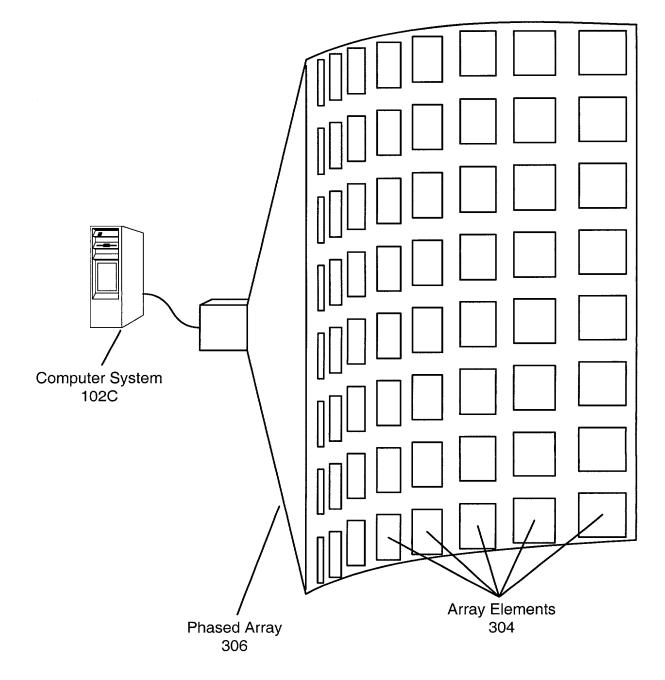


Figure 3C

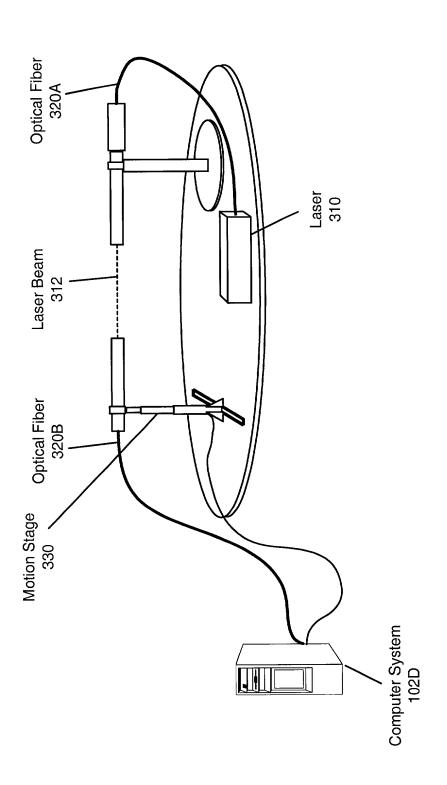
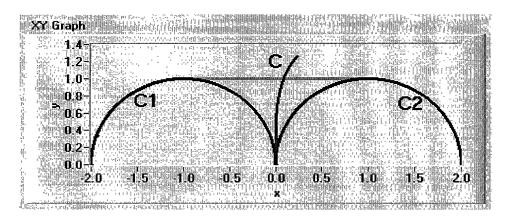


Figure 3D



The situation of Lemma 1
Figure 4A

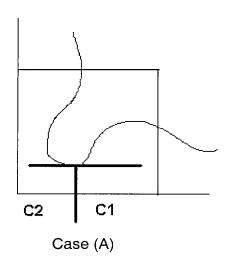


Figure 4B

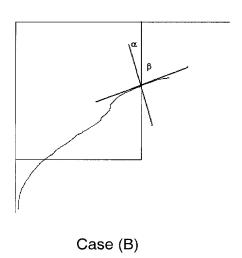
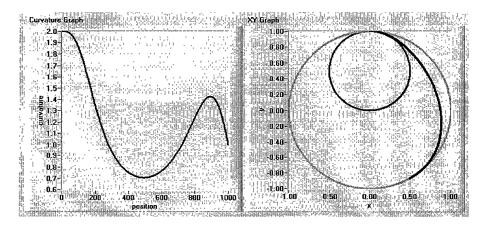
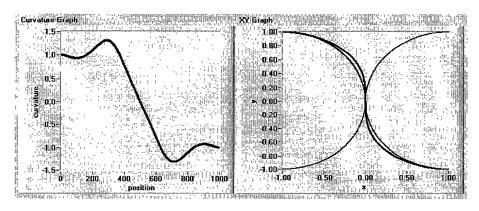


Figure 4C



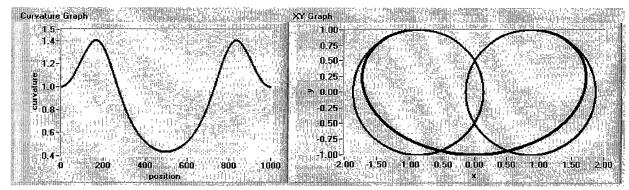
Smooth transition between two circles of different radii.





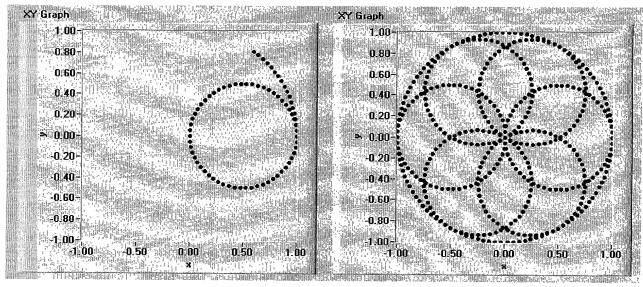
Smooth transition between two circles of same radius.

Figure 4E



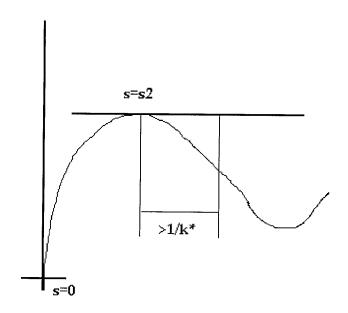
Transition between two unit circles of radius 1. The distance between the circles is sqrt(3)

Figure 4F

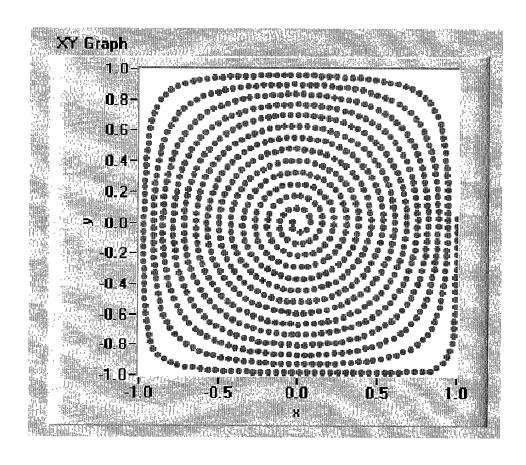


Beginning (left) and completion (right) of a scanning scheme where the curvature is below a certain value

Figure 5A



Construction of s2 and the subsequent part of the curve



Conformal Spiral.

Figure 6

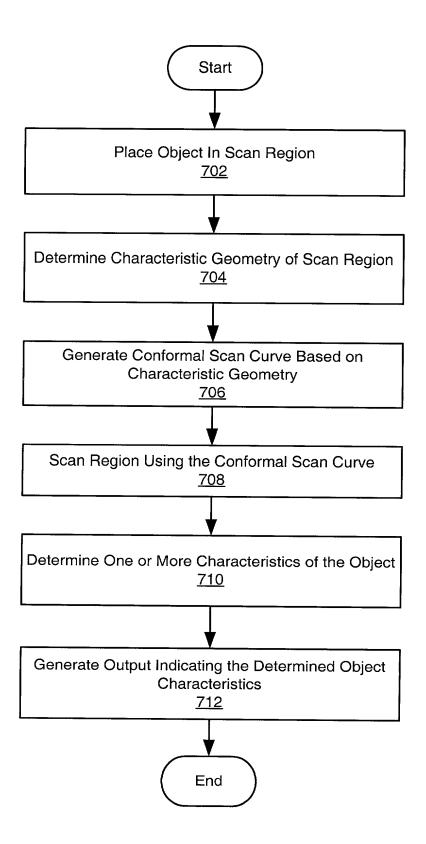
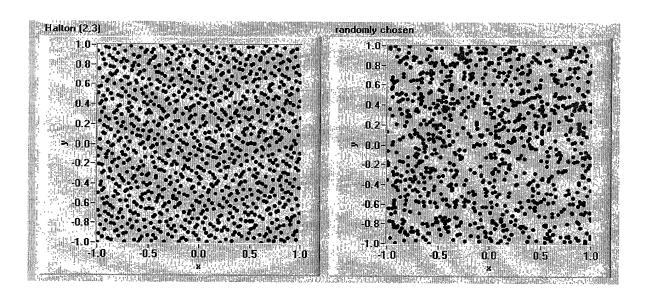
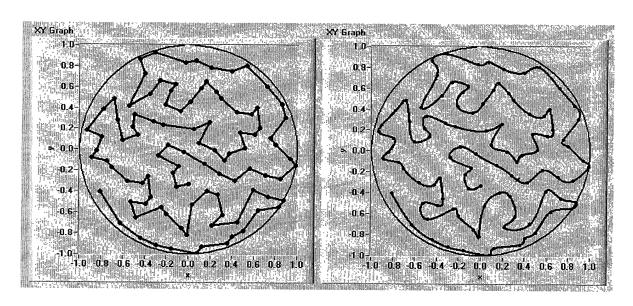


Figure 07



The first 1000 Halton points (left) and randomly chosen points (right)

Figure 8A



Original solution (left) and splined version (right).

Figure 8B

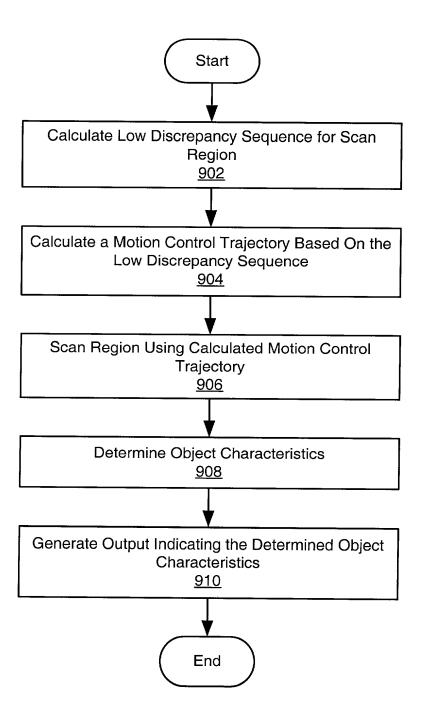
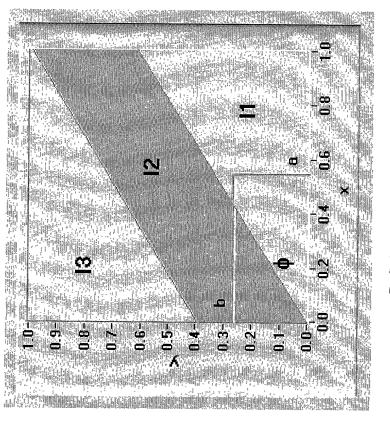


Figure 9



Definition of I1, I2, and I3

Figure 10

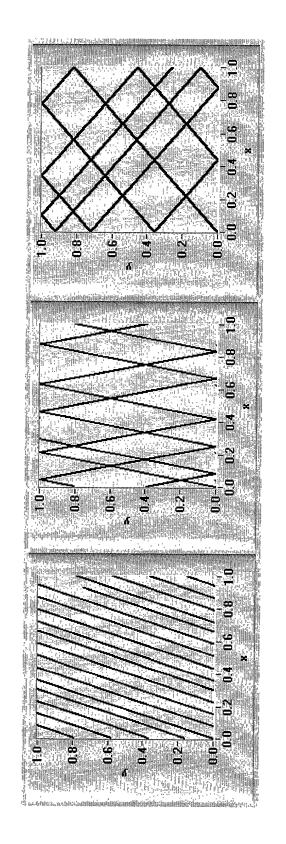


Figure 11A

Figure 11B

Figure 11C

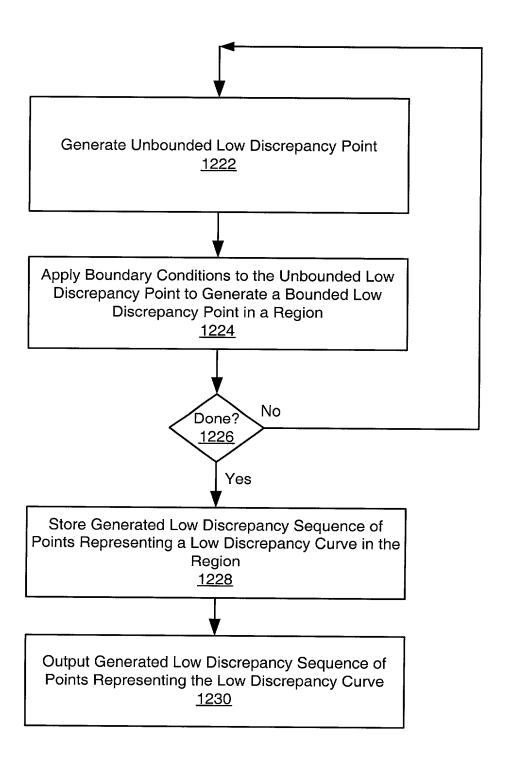


Figure 12A

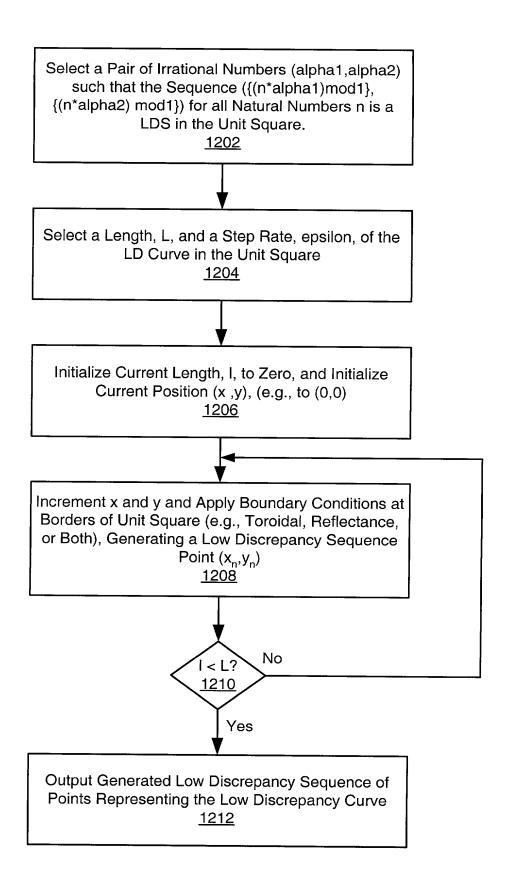
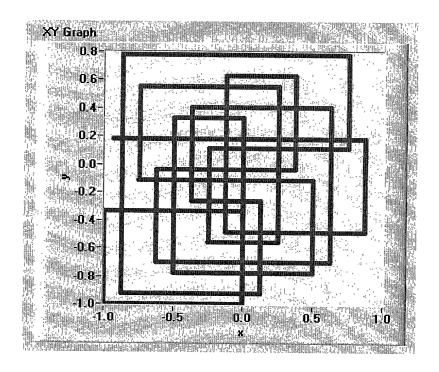
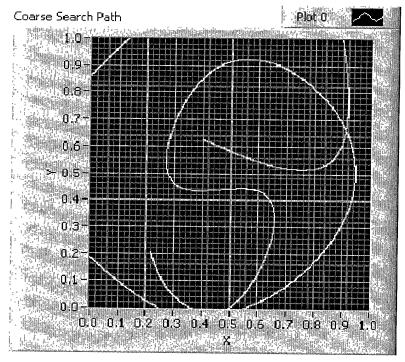


Figure 12B



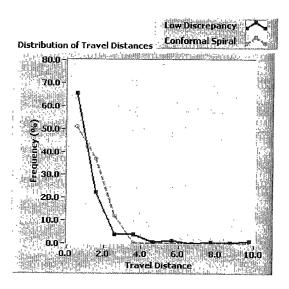
Beginning of a Low Discrepancy Curve based on a specific Halton Sequency in 2d





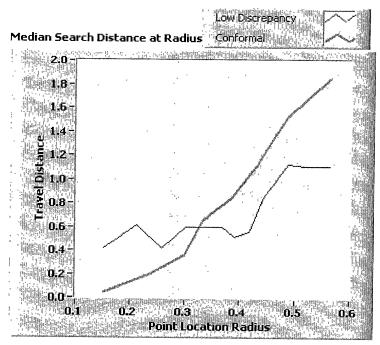
Splined Low Discrepancy Curve coarse search

Figure 13B



Comparison of Conformal Spiral and Low Discrepancy Searching

Figure 13C



Comparison of Travel Distance for Low Discrepancy Search and Conformal Spiral Search

Figure 13D

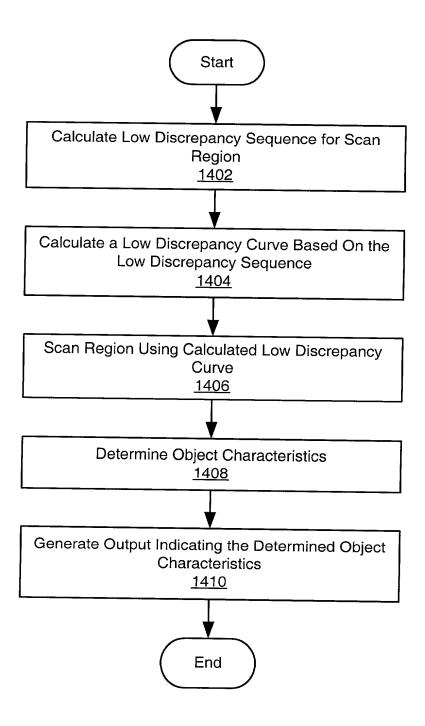
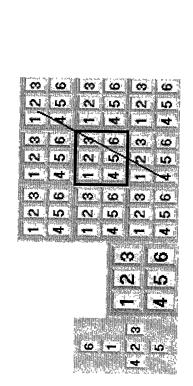
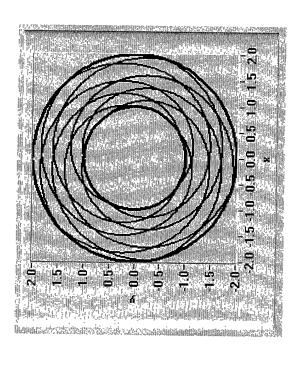


Figure 14



Tiling of the plane and relation to the surface of the unit cube

Figure 15A



Low-discrepancy curve in a ring

Figure 15B

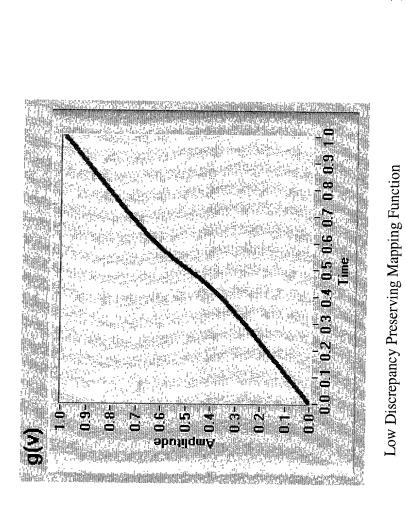
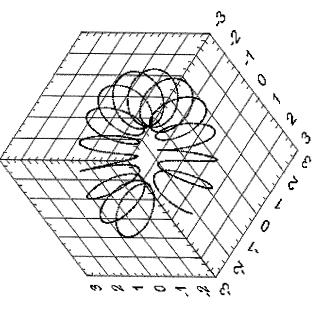
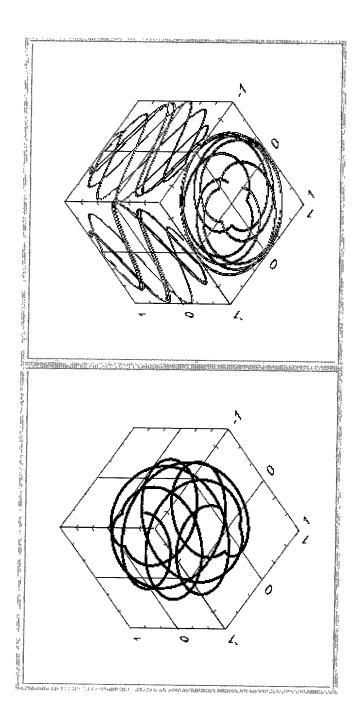


Figure 15C



Low-discrepancy curve filling the surface of a torus

Figure 15D



Low-discrepancy curve on a sphere (left) and projections (right)

Figure 16

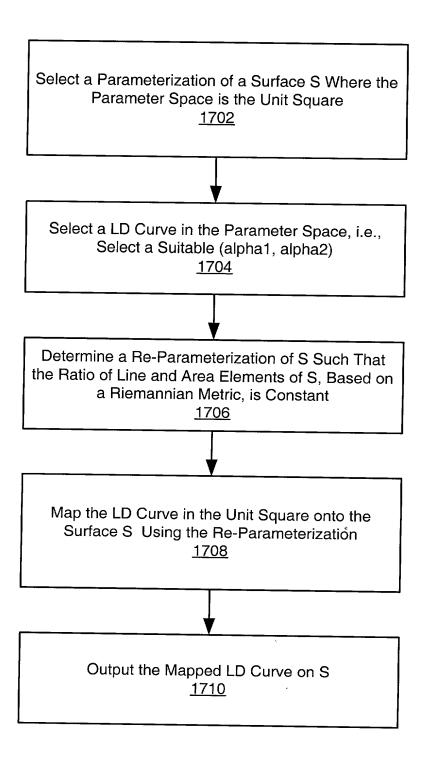
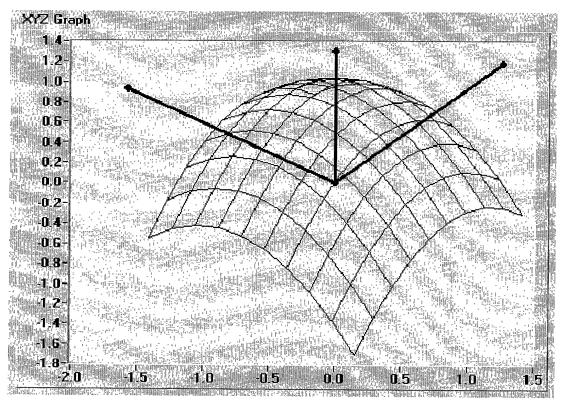
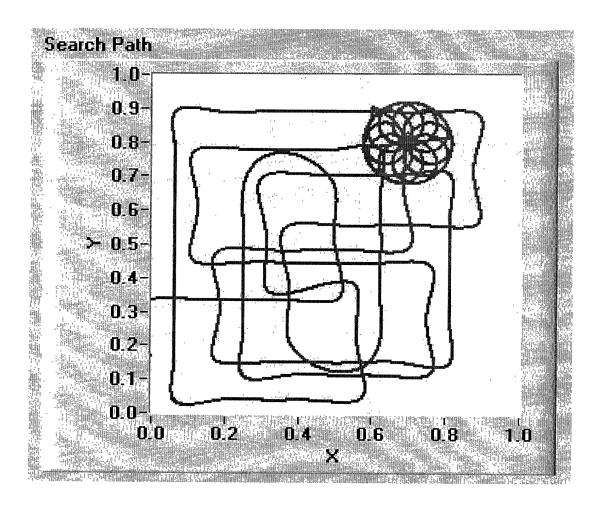


Figure 17



Surfaces can be scanned efficiently when the term low discrepancy sequence/curve can be generalized, e.g. based on metrics on the surface.

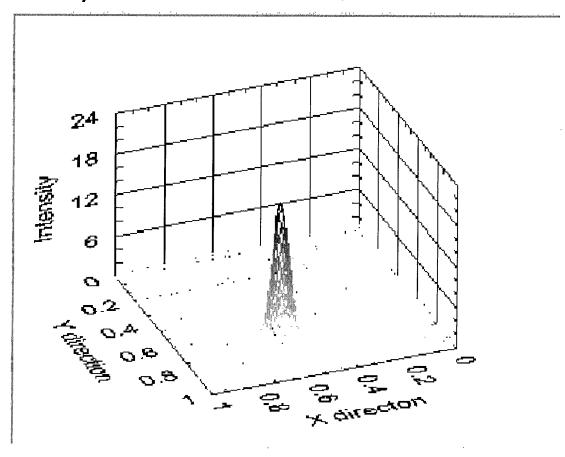
Figure 18



Splined Low Discrepancy Curve coarse search with refined final approach

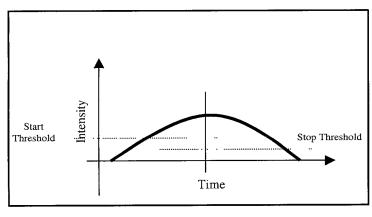
Figure 19

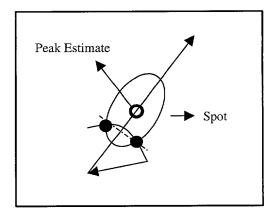
Intensity Field Distribution in Search Area



Beam intensity distribution in search area

Figure 20



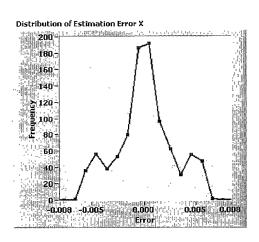


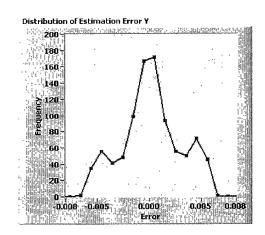
Location of the Peak

Initial Final Approach Move

Figure 21A

Figure 21B





Error distribution of the estimated peak X coordinate error (left) and Y coordinate error (right)

Figure 21C

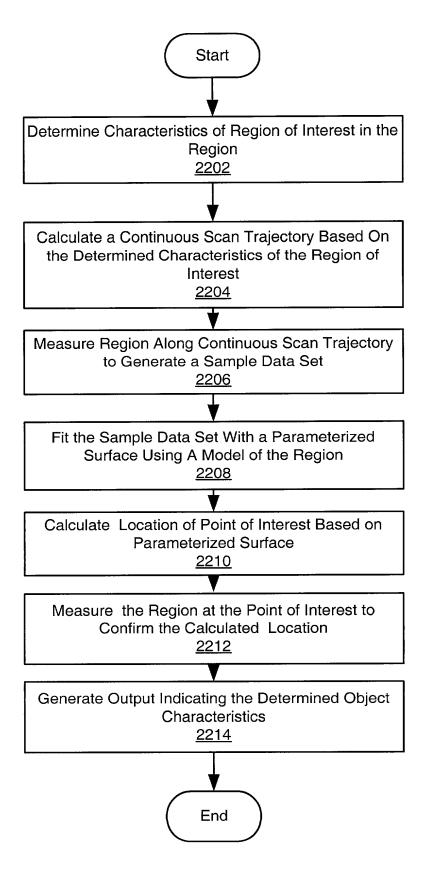


Figure 22

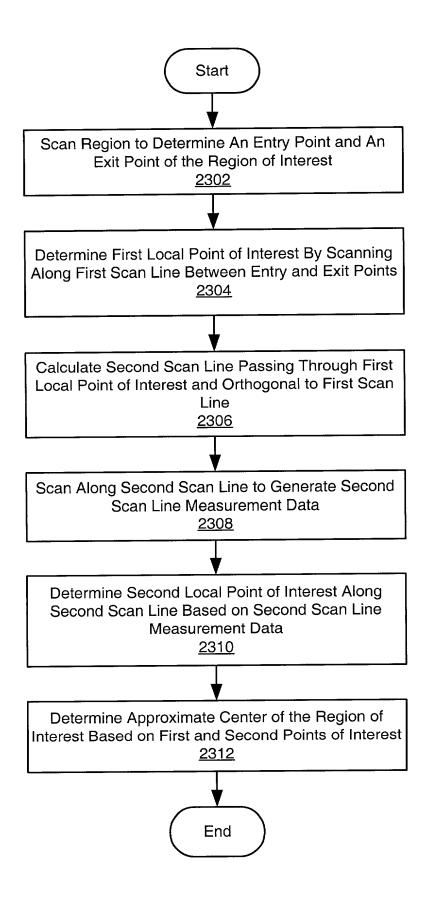


Figure 23